# Velodyne Lidar Alpha Prime **POWERING SAFE AUTONOMY**

## Alpha Prime

With the Alpha Prime, Velodyne Lidar delivers the optimal long-range sensor for autonomous mobility. The Alpha Prime's world-class combination of range, image clarity and field of view detects roadway objects with reliability and precision.

This state-of-the-art sensor generates high quality perception in a wide variety of light conditions, with advanced sensor-to-sensor interference mitigation, power efficiency, and thermal performance.

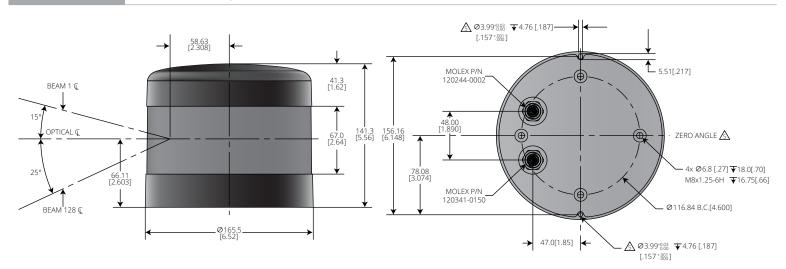
Providing long-range detection of low reflectance objects such as tire fragments, dark vehicles, asphalt, and pedestrians, the Alpha Prime enables autonomous operation within a broad range of settings, including urban and highway environments. A culmination of Velodyne's decade-plus experience engineering and manufacturing lidar, the Alpha Prime is powering safe autonomy.

## Alpha Prime at a glance

- · Best horizontal (360°) and vertical (40°) long-range sensor
  - 10% targets >220m typical
  - 5% targets >150m typical
  - Ground plane hits >90m typical
- High resolution (0.2° x 0.1°) and point density at full frame rate
- Industry-leading, proprietary sensor-to-sensor interference mitigation
- Strong performance with retro reflectors & sunlight
- New power efficiencies for maximum operating temperature
- · Proven, Class 1 eye-safe 903 nm technology
- Bottom connector, with cable length options
- 6 to 8-week lead time standard
- Multiple manufacturing sources available for qualified production projects



DIMENSIONS (Subject to change)



### Real-Time Lidar Sensor

The Alpha Prime provides ultra-high resolution 3-dimensional point clouds of the surrounding environment.

## Alpha Prime<sup>™</sup>



	Specifications <sup>1</sup> (Subject to change)
Sensor	<ul> <li>Channels: 128</li> <li>Measurement Range: up to 245m<sup>2</sup></li> <li>Detection: 150m on 5% NIST and 220m on 10% NIST</li> <li>Range Accuracy: +/- 3 cm (Typical)<sup>3</sup></li> <li>Return Modes: 1 or 2<sup>2</sup></li> <li>Horizontal Field of View: 360°</li> <li>Vertical Field of View: 40° (-25° to +15°)</li> <li>Minimum Angular Resolution (Vertical): 0.11° (non-linear distribution)</li> <li>Angular Resolution (Horizontal/Azimuth): 0.1° to 0.4° <sup>4</sup></li> <li>Frame Rate: 5 Hz to 20 Hz<sup>4</sup></li> <li>Integrated Web Server for Easy Monitoring and Configuration</li> </ul>
Laser	<ul> <li>Laser Product Classification: Class 1 - Eye -safe per IEC60825-1:2014</li> <li>Wavelength: ~ 903 nm</li> </ul>
Mechanical/E lectrical/ Operational	<ul> <li>Power Consumption: 22W (under typical conditions) <sup>5</sup></li> <li>Operating Voltage: 9V - 28V (including regulated power supply)</li> <li>Weight: ~ 3.5 kg (without cabling)</li> <li>Dimensions: See diagram on previous page</li> <li>Environmental Protection: IP67</li> <li>Operating Temperature: -20°C to 60°C (under typical conditions) <sup>6</sup></li> <li>Storage Temperature: -40°C to 105°C</li> </ul>
Output	<ul> <li>3D Lidar Data Points Generated <sup>2</sup> <ul> <li>Single Return Mode: ~ 2,400,000 points per second</li> <li>Dual Return Mode: ~ 4,800,000 points per second</li> </ul> </li> <li>Ethernet Connection: 1000Base-T</li> <li>UDP Packets Contain:         <ul> <li>Time of Flight Distance Measurement</li> <li>Calibrated Reflectivity Measurement</li> <li>Synchronized Time Stamps (µs resolution)</li> <li>System Diagnostic Data</li> </ul> </li> <li>GPS: \$GPRMC and \$GPGGA NMEA Sentence from GPS Receiver (GPS not included)</li> </ul>

- 1. These are projected specifications for final production parts. The specifications for any sample, prototype, or other non-final or pre-production products may be different from the specifications in this document. For more information, please contact Velodyne Sales.
- 2. Configuration dependent.
- 3. Typical accuracy refers to ambient wall test performance, excluding Retro, across most channels and may vary based on factors including but not limited to range, temperature and target reflectivity.
- 4. Fully characterized at 10 Hz.
- 5. Operating power may be affected by factors including but not limited to range, reflectivity and environmental conditions.
- 6. Operating temperatures may be affected by factors including but not limited to air flow and sun load.



